

STRUCTURE Silicon Monolithic Integrated Circuit

0.5ch Motor Driver for Digital Still Camera **PRODUCT SERIES**

BD6883GUL **TYPE**

FEATURES Built in 0.5 Constant-Voltage Drivers

● Absolute maximum ratings (Ta=25°C)

Parameter	Symbol	Limit	Unit
Power supply voltage	VCC	-0.5 to +6.5	V
Control input voltage	VIN	-0.5 to VCC+0.5	V
Input voltage for Constant-Voltage setting	VLIM	-0.5 to VCC+0.5	٧
Power dissipation	Pd	510 ^{※1}	mW
Operating temperature range	Topr	-25 to +85	°C
Junction temperature	Tjmax	+150	°C
Storage temperature range	Tstg	-55 to +150	°C
Half-bridge output current	lout	-200 to +200 ^{×2}	mA

^{*1} VIN is control input voltage (IN).

●Operating Conditions (Ta= -25°C to +85°C)

Parameter	Symbol	Min.	Тур.	Max.	Unit
Power supply voltage	VCC	2.5	3.0	5.5	V
Control input voltage	VIN	0	-	VCC	V
Input voltage for	VLIM	0		VCC	W
Constant-Voltage setting	VLIIVI	U	-	VCC	V
H-bridge output current	lout	-	-	±150 ^{**4}	mA

^{**} Must not exceed Pd or ASO.

The product described in this specification is a strategic product (and/or service) subject to COCOM regulations. It should not be exported without authorization from the appropriate government authorities.

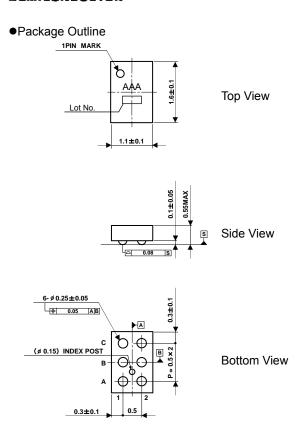
This product isn't designed for protection against radioactive rays.

Status of this document

^{**2} Reduced by 4.08mW/°C over 25°C, when mounted on a glass epoxy board (50mm × 58mm × 1.75mm; 8 layers).

^{**3} Must not exceed Pd, ASO, or Tjmax of 150°C.





●Pin Arrangement (Top View)

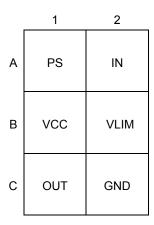
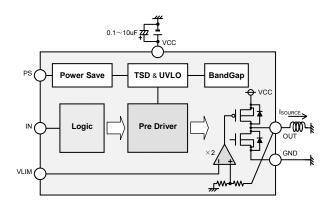


Fig.1 VCSP50L1 Package (Unit: mm)

Fig.2 BD6883GUL Pin Arrangement (Top View)

●Block Diagram



●Pin No. and Pin Name

No.	Name
1A	PS
2A	IN
1B	VCC
2B	VLIM
1C	OUT
2C	GND

Fig.3 BD6883GUL Block Diagram



Input-Output table

Constant-Voltage Drivers

	PS	IN	OUT
	Н	L	L
Logic	Н	Н	Н
	L	X	Z ^{**5}

H: High, L: Low, X: Don't care

Output voltage control

Output H voltage VOH [V] = $2.0 \times VLIM[V]$ (Typ.) VOH [V] = VCC[V] (VLIM > VCC/2)

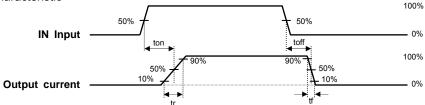
●BD6883GUL Electrical Characteristics (Unless otherwise specified Ta=25°C, VCC=3.0V)

Danamatan	Symbol Min.	Limit			Lloit	0 - 111
Parameter		Тур.	Max.	Unit	Conditions	
Overall						
Circuit current during standby operation	ICCST	-	0	10	μA	PS=0V
Circuit current	ICC	-	0.9	1.4	mA	PS=3V, VLIM=3V with no signal and load
Control input						
High level input voltage	VINH	2.0	-	VCC	V	
Low level input voltage	VINL	-	-	0.7	V	
High level input current	IINH	15	30	60	μA	VINH=3V pull-down resistor typ.100k Ω
Low level input current	IINL	-1	0	-	μA	VINL=0V
Constant-voltage Control	input					
Input current	IVLIM	-1.5	-0.5	-	uA	VLIM=0V
UVLO						
UVLO voltage	VUVL	1.6	-	2.4	V	
Constant-voltage Drive bl	ock					
Output ON Decistance	RONP	-	0.65	8.0	Ω	lo=-150mA
Output ON-Resistance	RONN	-	0.4	0.6	Ω	lo=+150mA
Output H voltage	VOH	1.9X VLIM	2.0X VLIM	2.1X VLIM	V	VLIM=1V, 10 Ω load
Turn-on time	ton		1.5	5	μs	lo=150mA, 10 Ω load
Turn-off time	toff	-	0.1	2	μs	lo=150mA, 10 Ω load
Rise time	tr	-	1.5	8	μs	lo=150mA, 10 Ω load
Fall time	tf		0.05	1	μs	lo=150mA, 10 Ω load

 $^{^{**5}}$ Z in Constant-Voltage Drivers is a state that POWER MOS has been turned off with the top and bottom. But feed back resistance (20k Ω : Typ) for output H voltage setting is connected between OUT and GND.



Output AC characteristic



The voltage and current waveform show the turn on time, turn off time, rise time and fall time when input pulse was applied at IN.

Operation Notes

(1) Absolute maximum ratings

Use of the IC in excess of absolute maximum ratings such as the applied voltage or operating temperature range (Topr) may result in IC damage. Assumptions should not be made regarding the state of the IC (short mode or open mode) when such damage is suffered. The implementation of a physical safety measure such as a fuse should be considered when use of the IC in a special mode where the absolute maximum ratings may be exceeded is anticipated.

(2) Power supply lines

Regenerated current may flow as a result of the motor's back electromotive force. Insert capacitors between the power supply and ground pins to serve as a route for regenerated current. Determine the capacitance in full consideration of all the characteristics of the electrolytic capacitor, because the electrolytic capacitor may loose some capacitance at low temperatures. If the connected power supply does not have sufficient current absorption capacity, regenerative current will cause the voltage on the power supply line to rise, which combined with the product and its peripheral circuitry may exceed the absolute maximum ratings. It is recommended to implement a physical safety measure such as the insertion of a voltage clamp diode between the power supply and GND pins.

(3) Ground potential

Ensure a minimum GND pin potential in all operating conditions.

(4) Setting of heat

Use a thermal design that allows for a sufficient margin in light of the power dissipation (Pd) in actual operating conditions.

(5) Actions in strong magnetic field

Use caution when using the IC in the presence of a strong magnetic field as doing so may cause the IC to malfunction.

(6) ASO

When using the IC, set the output transistor for the motor so that it does not exceed absolute maximum ratings or ASO.

(7) Thermal shutdown circuit

This IC incorporates a TSD (thermal shutdown) circuit (TSD circuit). If the temperature of the chip reaches the following temperature, the motor coil output will be opened. The thermal shutdown circuit (TSD circuit) is designed only to shut the IC off to prevent runaway thermal operation. It is not designed to protect the IC or guarantee its operation. Do not continue to use the IC after operating this circuit or use the IC in an environment where the operation of this circuit is assumed.

TSD ON temperature [°C]	Hysteresis temperature [°C]
(Typ.)	(Typ.)
175	25

(8) Ground Wiring Pattern

When using both small signal and large current GND patterns, it is recommended to isolate the two ground patterns, placing a single ground point at the application's reference point so that the pattern wiring resistance and voltage variations caused by large currents do not cause variations in the small signal ground voltage. Be careful not to change the GND wiring pattern of any external components, either.

Notes

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